RT-9 ANCHOR DRIVE

TWO SPEED DRIVE UNIT | PN 610058

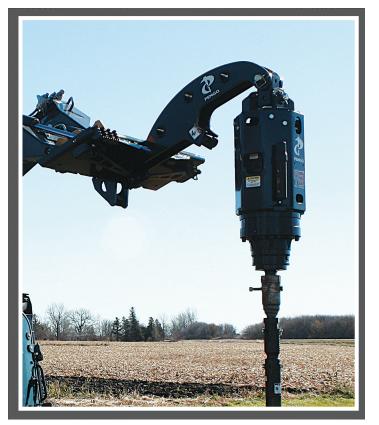
Removable

Top Section



used for anchor installation

Kits include Pin, Displays, Anti-Rotation Block, Mount, Cable and Stylus.



The RT-9 Anchor drive is perfect for the small anchor installation and drilling projects. The auto shift feature allows the drive to automatically shift between high speed and low torque and low speed high torque depending on the input flow. If you chose to use this drive for drilling, select the Pengo TriMax[®] or Utility auger for best results.

Standard crossover pressure relief system that is designed to protect the motor from pressure spikes and potential overload conditions

> Attached Manual Holder for Quick Access

Highly Efficient Gearbox designed for long duty cycles

> 2 1/2" Hex Output Shaft –

ENGO

HYDRAULIC MOTOR INFORMATION			
Displacement	11.9 cu/in (195cc)		
Motor Type	Two Speed Bi-Directional		
Motor Output Shaft	1 1/4" Spline 14T		
Motor Mount	SAE - C 4 Bolt		
Motor Ports	1 5/8" - 12-UN-2B		
Cross Over Pressure Relief	Set at 3100 PSI		
PLANETARY GEARBOX INFORMATION			
PLANETARY GEARB	OX INFORMATION		
PLANETARY GEARB Gearbox Type	OX INFORMATION Planetary Two Stage		
Gearbox Type	Planetary Two Stage		
Gearbox Type Reduction Ratio	Planetary Two Stage 25.36:1		
Gearbox Type Reduction Ratio Output Shaft	Planetary Two Stage 25.36:1 2 1/2" Hex		
Gearbox Type Reduction Ratio Output Shaft Internal Oil Capacity	Planetary Two Stage 25.36:1 2 1/2" Hex 2.0 Gallons		

RT-9 ANCHOR DRIVE

REFERENCE SPEED CHART Flow GPM (Liter) Low (rpm) High (rpm) 20 (75) 25 13 30 (113) 19 38 40 (151) 25 50 50 (190) 31 63

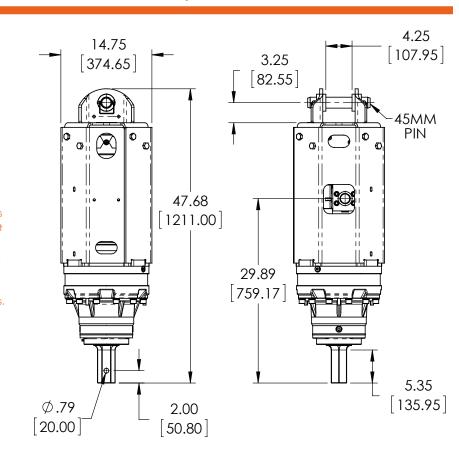
Pressure (psi)	THEORETICAL Torque (ft/lb)	ACTUAL Torque (ft/lb)
1000	2002	1642
1200	2402	1970
1400	2802	2298
1600	3203	8686
1800	3603	8954
2000	4004	3283
2200	4404	3611
2400	4805	3940
2600	5205	4268
2800	5605	4596
3000	6006	4925

lote that both theoretical

and actual torque values are listed, but that Pengo recommends to go by ACTUAL torque listings.

5	REFERE	NCE TORQUE CH	ART (HT / LS)
OUTPUT	Pressure (psi)	THEORETICAL Torque (ft/lb)	ACTUAL Torque (ft/lb)
	1000	4004	3283
EEU	1200	4805	3940
2	1400	5605	4596
	1600	6406	5253
S	1800	7207	5910
	2000	8008	6567
С У	2200	8809	7223
	2400	9610	7880
	2600	10410	8536
E り F	2800	11211	9193
Ē	3000	12012	9850







Pengo lists output speeds at both theoretical and actual. Actual torque numbers are NOT listed at 100% efficiency. Maximum efficiencies have been applied to the torque and speed charts according to the manufacturer's recommendations. Speed and torque output are dependent on the overall system efficiencies associated with the prime movers hydraulic system. When the purchaser is determining criteria for specific applications please contact Pengo. Pengo has made every attempt to present accurate and suitable information published in this document. This document should be used for information and comparative purposes only. When application-specific information is required, please contact Pengo.

2-Speed Models must have a minimum of 20GPM

RT-12 ANCHOR DRIVE

TWO SPEED DRIVE UNIT | PN 610059





excavator size 6T - 12T connections ∰ 2½	WEIGHT NOT RECOM FOR DRILLING	
TRULINK TORQUE PIN RT-12 is outfitted to fit these TruLink® Torque Monitor Syst	ems.	TruLink 2.0 Class 1 with 7" Display PN 615070

Kits include Pin, Displays, Anti-Rotation Block, Mount, Cable and Stylus.



The RT-12 Anchor drive is perfect anchor installation projects when using a skid steer, mini-excavator or backhoe. This drive may also be used for some drilling applications with the Pengo Utility or Excavator auger system.

Gearbox Type Reduction Ratio

Output Shaft

Oil Type

Internal Oil Capacity

Shaft Pull Out (lbs.)

PLANETARY GEARBOX INFORMATION

25.36:1

22,500

2 1/2" Hex

2.0 Gallons

SAE 80W90 GL-5

Planetary Two Stage

14.75

RT-12 ANCHOR DRIVE

REFERENCE SPEED CHART Flow GPM (Liter) Low (rpm) High (rpm) 20 (75) 10 21 30 (113) 15 32 40 (151) 20 43 50 (190) 25 54

REFERENCE TORQUE CHART (LT / HS)			Note
Pressure (psi)	THEORETICAL Torque (ft/lb)	ACTUAL Torque (ft/lb)	that theoi
1000	2338	1917	and
1200	2806	2301	torqu are li
1400	3274	2685	that
1600	3742	3068	reco
1800	4209	3451	to go
2000	4677	3835	ACTL
2200	5145	4219	torqu
2400	5613	4603	
2600	6081	4986	
2800	6548	5369	
3000	7016	5753	

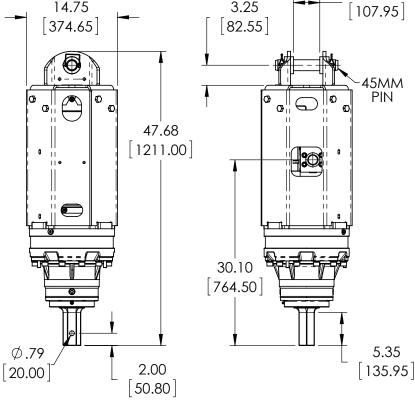
LOW TORQUE/HIGH SPEED OUTPUT

UT	REFERE	NCE TORQUE CH	ART (HT / LS)
OUTPUT	Pressure (psi)	THEORETICAL Torque (ft/lb)	ACTUAL Torque (ft/lb)
	1000	5012	4110
	1200	6014	4931
SPEED	1400	7017	5754
	1600	8019	6576
0	1800	9022	7398
TORQUE/LOW	2000	10024	8220
ы С	2200	11027	9042
OR O	2400	12029	9864
	2600	13032	10686
нон	2800	14034	11508
Ĭ	3000	15037	12330



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Pengo lists output speeds at both theoretical and actual. Actual torque numbers are NOT listed at 100% efficiency. Maximum efficiencies have been applied to the torque and speed charts according to the manufacturer's recommendations. Speed and torque output are dependent on the overall system efficiencies associated with the prime movers hydraulic system. When the purchaser is determining criteria for specific applications please contact Pengo. Pengo has made every attempt to present accurate and suitable information published in this document. This document should be used for information and comparative purposes only. When application-specific information is required, please contact Pengo.

2-Speed Models must have a minimum of 20GPM

3.25

4.25

RT-20 ANCHOR DRIVE

TWO SPEED DRIVE UNIT | PN 610060



HYDRAULIC MOTOR INFORMATION			
Displacement	11.9 cu/in (195cc)		
Motor Type	Two Speed Bi-Directional		
Motor Output Shaft	1 1/4" Spline 14T		
Motor Mount	SAE - C 4 Bolt		
Motor Ports	1 5/8" - 12-UN-2B		
Cross Over Pressure Relief	Set at 3100 PSI		
PLANETARY GEARBOX INFORMATION			
Gearbox Type	Planetary Three Stage		
Gearbox Type Reduction Ratio			
	Planetary Three Stage		
Reduction Ratio	Planetary Three Stage 60.56:1		
Reduction Ratio Output Shaft	Planetary Three Stage 60.56:1 3 1/2" Hex		

EXCAVATOR SIZE [2T - 2DT CONNECTIONS ☆ ③" TRULINK TORQUE PIN RT-20 is outfitted to fit these TruLink® Torque Monitor Systems. WEIGHT NOT RECOMMENDED FOR DRILLING TruLink 2.0 Class 1 with 7" Display PN | 615070

used for anchor installation

Kits include Pin, Displays, Anti-Rotation Block, Mount, Cable and Stylus.



When the job calls for larger anchor installation using a backhoe or excavator turn to the RT-20. The auto shift feature allows the drive to automatically shift between high speed and low torque and low speed high torque depending on the input flow.

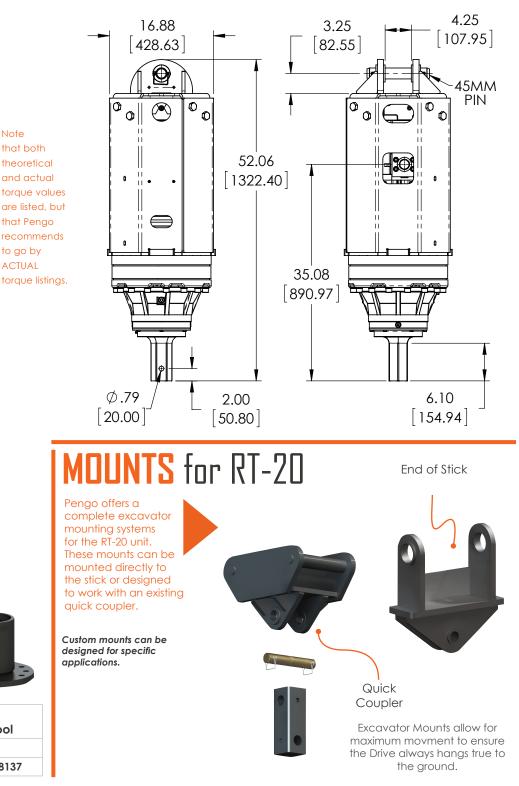
RT-20 ANCHOR DRIVE

REFERENCE SPEED CHART Flow GPM (Liter) Low (rpm) High (rpm) 20 (75) 10 5 30 (113) 8 15 40 (151) 10 20 50 (190) 13 25

υT	REFERE	NCE TORQUE CH	ART (LT / HS)	Note
OUTPUT	Pressure (psi)	THEORETICAL Torque (ft/lb)	ACTUAL Torque (ft/lb)	that I theor
	1000	4781	3777	and
SPEED	1200	5737	4532	torqu are lis
SPI	1400	6693	5287	that F
H	1600	7649	6043	recor
TORQUE/HIGH	1800	8605	6798	to go
Ë,	2000	9562	7554	ACTU
n	2200	10518	8309	torqu
RO	2400	11474	9064	
10	2600	12430	9820	
ГОW	2800	13386	10575	
D D	3000	14343	11331	

Ц	REFERE	NCE TORQUE CH	ART (HT / LS)
OUTP	Pressure (psi)	THEORETICAL Torque (ft/lb)	ACTUAL Torque (ft/lb)
	1000	9562	7554
EED	1200	11474	9064
SPI	1400	13386	10575
≥	1600	15299	12086
0	1800	17211	13597
RQUE/LO	2000	19124	15108
л С	2200	21036	16618
SR	2400	22948	18129
10	2600	24861	19640
Ч С	2800	26773	21151
Ĭ	3000	28686	22662

45MM Pin LBS | 7 PN | 660558 45MM Link Arm LBS | 46 PN | 660555 PN | 158137 2-Speed Models must have a minimum of 20GPM



Pengo lists output speeds at both theoretical and actual. Actual torque numbers are NOT listed at 100% efficiency. Maximum efficiencies have been applied to the torque and speed charts according to the manufacturer's recommendations. Speed and torque output are dependent on the overall system efficiencies associated with the prime movers hydraulic system. When the purchaser is determining criteria for specific applications please contact Pengo. Pengo has made every attempt to present accurate and suitable information published in this document. This document should be used for information and comparative purposes only. When application-specific information is required, please contact Pengo.

RT-30 ANCHOR DRIVE

VARIABLE SPEED DRIVE UNIT | PN 610061



used for anchor installation



HYDRAULIC MOTOR INFORMATION			
Displacement	13.9 cu/in (195cc)		
Motor Type	Two Speed Bi-Directional		
Motor Output Shaft	1 1/4" Spline 14T		
Motor Mount	SAE - C 4 Bolt		
Motor Ports	1 5/8" - 12-UN-2B		
Cross Over Pressure Relief	Set at 3100 PSI		
PLANETARY GEARBOX INFORMATION			
PLANETARY GEARB	OX INFORMATION		
PLANETARY GEARB Gearbox Type	OX INFORMATION Planetary Three Stage		
Gearbox Type	Planetary Three Stage		
Gearbox Type Reduction Ratio	Planetary Three Stage 69.7:1		
Gearbox Type Reduction Ratio Output Shaft	Planetary Three Stage 69.7:1 4" Square		
Gearbox Type Reduction Ratio Output Shaft Internal Oil Capacity	Planetary Three Stage 69.7:1 4" Square 3.1 Gallons		

excavator size 15T - 25T	WEIGHT	LBS 1220
	NOT RECOM FOR DRILLIN	
TRULINK TORQUE PIN RT-30 is outfitted to fit these Trulink® Torque Monitor Syst		TruLink 2.0 Class 2 with 7" Display PN 615071

Kits include Pin, Displays, Anti-Rotation Block, Mount, Cable and Stylus.

TruLink[®] Torque Monitor Systems.



Use The RT-30 Anchor drive for larger projects with an excavator. The auto shift feature allows the drive to automatically shift between high speed and low torque and low speed high torque depending on the input flow.

RT-30 ANCHOR DRIVE

REFERENCE SPEED CHART Flow GPM (Liter) Low (rpm) High (rpm) 20 (75) 4 8 30 (113) 6 11 40 (151) 8 15 50 (190) 9 19

REFERENCE TORQUE CHART (LT / HS)		
Pressure (psi)	THEORETICAL Torque (ft/lb)	ACTUAL Torque (ft/lb)
1000	6428	5078
1200	7713	6093
1400	8999	7109
1600	10285	8125
1800	11570	9140
2000	12856	10156
2200	14141	11171
2400	15427	12187
2600	16713	13203
2800	17998	14218
3000	19284	15234

that both theoretical and actual torque values are listed, but

Note

that Pengo recommends to go by ACTUAL torque listings.

IJ	REFERENCE TORQUE CHART (HT / LS)		
OUTPUT	Pressure (psi)	THEORETICAL Torque (ft/lb)	ACTUAL Torque (ft/lb)
	1000	12856	10156
EED	1200	15427	12187
SPI	1400	17998	14210
	1600	20570	16250
Õ	1800	23141	18281
<u> </u>	2000	25712	20312
л С	2200	28283	22344
TORQUE/LOW	2400	30855	24375
	2600	33426	26407
ЧO	2800	35997	28438
Ĭ	3000	38569	30470



20.25 6.25 5.00 514.35 158.75 127.00 Ø ကြာ ര ത a 0 C 75MM PIN 62.17 1579.11 ۵ 0 \square \bigcirc 0 ٥ 11 40.55 1030.06 10.98 279.00 Ø1.06 2.00 27.00 50.80

2-Speed Models must have a minimum of 20GPM



Quick Coupler

Excavator Mounts allow for maximum movment to ensure the Drive always hangs true to the ground.

Pengo lists output speeds at both theoretical and actual. Actual torque numbers are NOT listed at 100% efficiency. Maximum efficiencies have been applied to the torque and speed charts according to the manufacturer's recommendations. Speed and torque output are dependent on the overall system efficiencies associated with the prime movers hydraulic system. When the purchaser is determining criteria for specific applications please contact Pengo. Pengo has made every attempt to present accurate and suitable information published in this document. This document should be used for information and comparative purposes only. When application-specific information is required, please contact Pengo.

RT-40 ANCHOR DRIVE

TWO SPEED DRIVE UNIT | PN 610480



HYDRAULIC MOTO	DR INFORMATION
Displacement	15.8 cu/in (195cc)
Motor Type	Two Speed Bi-Directional
Motor Output Shaft	1 1/4" Spline 14T
Motor Mount	SAE - C 4 Bolt
Motor Ports	1 5/8" - 12-UN-2B
Cross Over Pressure Relief	Set at 3100 PSI
PLANETARY GEARB	OX INFORMATION
PLANETARY GEARB Gearbox Type	OX INFORMATION Planetary Three Stage
Gearbox Type	Planetary Three Stage
Gearbox Type Reduction Ratio	Planetary Three Stage 83.78:1
Gearbox Type Reduction Ratio Output Shaft	Planetary Three Stage 83.78:1 130mm Square

EXCAVATOR SIZE 15T - 25T CONNECTIONS B B CONNECTIONS CONNECTIONS CONNECTIONS B CONNECTIONS CONNECTI

Kits include Pin, Displays, Anti-Rotation Block, Mount, Cable and Stylus.

TruLink® Torque Monitor Systems.



The RT-40 Anchor drive is perfect for the larger anchor installation projects when using an excavator. The auto shift feature allows the drive to automatically shift between high speed and low torque and low speed high torque depending on the input flow.

25 \$ || **40% 4**

used for anchor installation

PN | 615071

RT-40 ANCHOR DRIVE

REFERENCE SPEED CHART			
Flow GPM (Liter)	Low (rpm)	High (rpm)	
20 (75)	3	6	
30 (113)	4	9	
40 (151)	6	12	
50 (190)	7	15	

UT	REFERE	NCE TORQUE CH	ART (LT / HS)	Note
OUTPUT	Pressure (psi)	THEORETICAL Torque (ft/lb)	ACTUAL Torque (ft/lb)	that theor
	1000	7726	6104	and a
EED	1200	9272	4325	torqu are lis
SPI	1400	10817	8545	that F
H	1600	12362	9766	recor
TORQUE/HIGH	1800	13908	10987	to go
T-	2000	15453	12208	ACTU
n	2200	16998	13428	torqu
R O	2400	18544	14650	
10	2600	20089	15870	
low	2800	21634	17091	
2	3000	23180	18312	

Ы	REFERENCE TORQUE CHART (HT / LS)		
OUTP	Pressure (psi)	THEORETICAL Torque (ft/lb)	ACTUAL Torque (ft/lb)
	1000	17664	13955
EED	1200	21197	16746
SPI	1400	24730	19537
3	1600	28263	22328
TORQUE/LO	1800	31796	25119
Ē	2000	35329	279100
D C	2200	38862	30701
R K	2400	42395	33492
	2600	45928	36283
Ч С	2800	49461	39074
Ī	3000	52994	41865

 75MM Pin

 LBS | 10

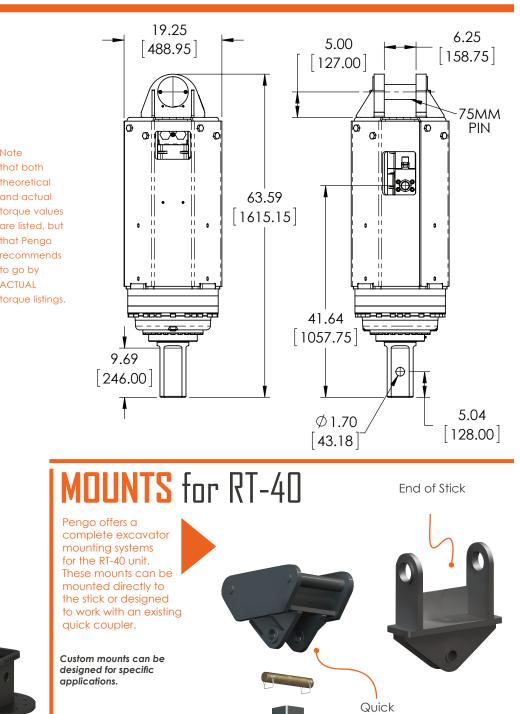
 PN | 660554

 75MM Link Arm

 LBS | 137

 PN | 610202

 PN | 610301



Pengo lists output speeds at both theoretical and actual. Actual torque numbers are NOT listed at 100% efficiency. Maximum efficiencies have been applied to the torque and speed charts according to the manufacturer's recommendations. Speed and torque output are dependent on the overall system efficiencies associated with the prime movers hydraulic system. When the purchaser is determining criteria for specific applications please contact Pengo. Pengo has made every attempt to present accurate and suitable information published in this document. This document should be used for information and comparative purposes only. When application-specific information is required, please contact Pengo.

2-Speed Models must have a minimum of 20GPM

Coupler

Excavator Mounts allow for

maximum movment to ensure

the Drive always hangs true to

the ground.